

DAFTAR PUSTAKA

- Asada, H. H. (2012). *Introduction to Robotics*. Boston : Massachusetts Institute of Technology.
- Automatic thresholding using a modified valley emphasis*. (2020). Retrieved from IET Research: <https://ietresearch.onlinelibrary.wiley.com/doi/10.1049/iet-ipr.2019.0176>
- Bolz, H. A., & Hagemann, G. E. (1958). *Materials Handling Handbook*. Ronald Press.
- Bradski, G., & Kaehler, A. (2008). *Learning OpenCV*. Sebastopol: O'Reilly Media, Inc.
- Budiharto, W., & Purwanto, D. (2009). *Robot vision: Teknik Membangun Robot Cerdas Masa Depan*. Yogyakarta: ANDI.
- FCA. (2007). *System Development*. Virginia.
- Heragu, S., & Ekren, Y. (2009). *Materials Handling System Design*. Louisville: University of Louisville.
- Jeffreys, H. and Jeffreys, B. S. "*Lagrange's Interpolation Formula*." §9.011 in *Methods of Mathematical Physics*, 3rd ed. Cambridge, England: Cambridge University Press, p. 260, 1988.
- Kendall, K. E., & Kendall, J. E. (2006). *Systems Analysis and Design*. New Jersey: Pearson.
- Kossiakoff, A., Seymour, S. J., Flanigan, D. A., & Biemer, S. M. (2020). *Systems Engineering Principles and Practice*. Hoboken: Wiley.
- Lutz, M. (2016). *Learning Python*. Sebastopol: O'Reilly.
- Magician*. (2023). Retrieved from *Dobot Magician*: <https://www.dobot-robots.com/products/education/magician.html>
- Mathematical Interpolation. Wikipedia. 2016. Available online: <https://en.wikipedia.org/wiki/Interpolation> (accessed on 11 February 2016).
- OpenCV Overview*. (2021). Retrieved from Tutorialspoint:https://www.tutorialspoint.com/opencv/opencv_overview.htm

Python: Grayscale of Images using OpenCV. (2023, January 4). Retrieved from Geeks for Geeks:<https://www.geeksforgeeks.org/Python-grayscale-of-images-using-opencv/>

Ray, S. (2008). *Introduction to Materials Handling*. New Delhi: New Age.

Relly Victoria Virgil Petrescu / *American Journal of Engineering and Applied Sciences* 2023, 16 (2): 56.75

Robotics Tutorial: How to Build Robotic Arm with Dobot. (2023, May 17). Retrieved from Dobot Robots: <https://www.dobot-robots.com/insights/news/robotics-tutorial-how-to-build-robotic-arm-with-dobot.html>

Saha, S. K. (2014). *Introduction to Robotics*. New Delhi: McGraw Hill Education.

Stephens, M. P., & Meyers, F. E. (2013). *Manufacturing Facilities Design and Material Handling*. West Lafayette: Purdue University.

Weisstein, E.W. *Lagrange Interpolating Polynomial from MathWorld—A Wolfram Web Resource.* 2018. Available online: <http://mathworld.wolfram.com/LagrangeInterpolatingPolynomial.html> (accessed on 1 June 2018).